

Technical Outline of the Session:

This special session focuses on the latest advancements in the control, guidance, and navigation of robotic systems, including aerial, ground, and underwater platforms. The session will highlight both theoretical approaches and practical solutions in areas such as nonlinear and adaptive control, sensor fusion, localization, path planning, and real-time navigation. Special attention will be given to emerging techniques involving AI and machine learning, swarm coordination, and robust operation in complex and uncertain environments.

We aim to bring together experts from academia, research institutions, and industry to share innovations, field-tested applications, and new challenges in robotic autonomy. Topics may include GPS-denied navigation, control system integration, trajectory optimisation, and autonomous mission planning.

• Topic of the Session includes, but are not limited to:

- Nonlinear and adaptive control
- Sensor fusion, localisation, path planning, and real-time navigation
- GPS-denied navigation, control system integration
- Trajectory optimisation and autonomous mission planning
- Vision and camera-based navigation control
- Al systems in control and navigation
- Path planning with Al agents
- Centralised and decentralised control strategies in robotics
- Simulation and virtual environment for control testing in robotics
- Robotics mobility control and soft robotics control systems

Important Dates:

- Special Session Paper Submission Due : June 15, 2025
- Notification of Paper Acceptance : July 31, 2025
- Camera Ready Paper Submission Due : August 31, 2025

: October 30, 2025

Regular Registration Due







Submission Portal

For queries, email: ss_stpec2025@nitgoa.ac.in

https://nitgoa.ac.in/STPEC2025/specialsessions.html